

RGB-D Salient Object Detection with Cross-Modality Modulation and Selection

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https://li-chongyi.github.io/Proj_ECCV20

Abstract. In this supplementary material, we first provide more visual results in Sec. 1, then analyze the side outputs of our network in Sec. 2, and finally compare the model sizes of different SOD methods in Sec. 3.

1 Visual Results

In this section, we provide more visual results of all the compared methods on the testing datasets in Fig. 1. In comparison, our method yields more complete, sharp, and edge-preserving saliency detection results, and effectively suppresses the cluttered backgrounds.

2 Side Outputs

In this section, we analyze the side outputs of our network. Since our network produces five saliency maps with a resolution ranging from 14×14 to 224×224 with a scale of 2, it can provide diverse choices based on salient object detection (SOD) accuracy and inference speed.

In some cases that require faster inference speed, we can perform early stopping on the inference and directly up-sample (such as by linear interpolation) the side output in the higher level to the same size of input RGB image as the final result. In this way, the inference time can be reduced when the SOD performance decreases accordingly as shown in Table 1. Visual examples of our side outputs in different levels are shown in Fig. 2.

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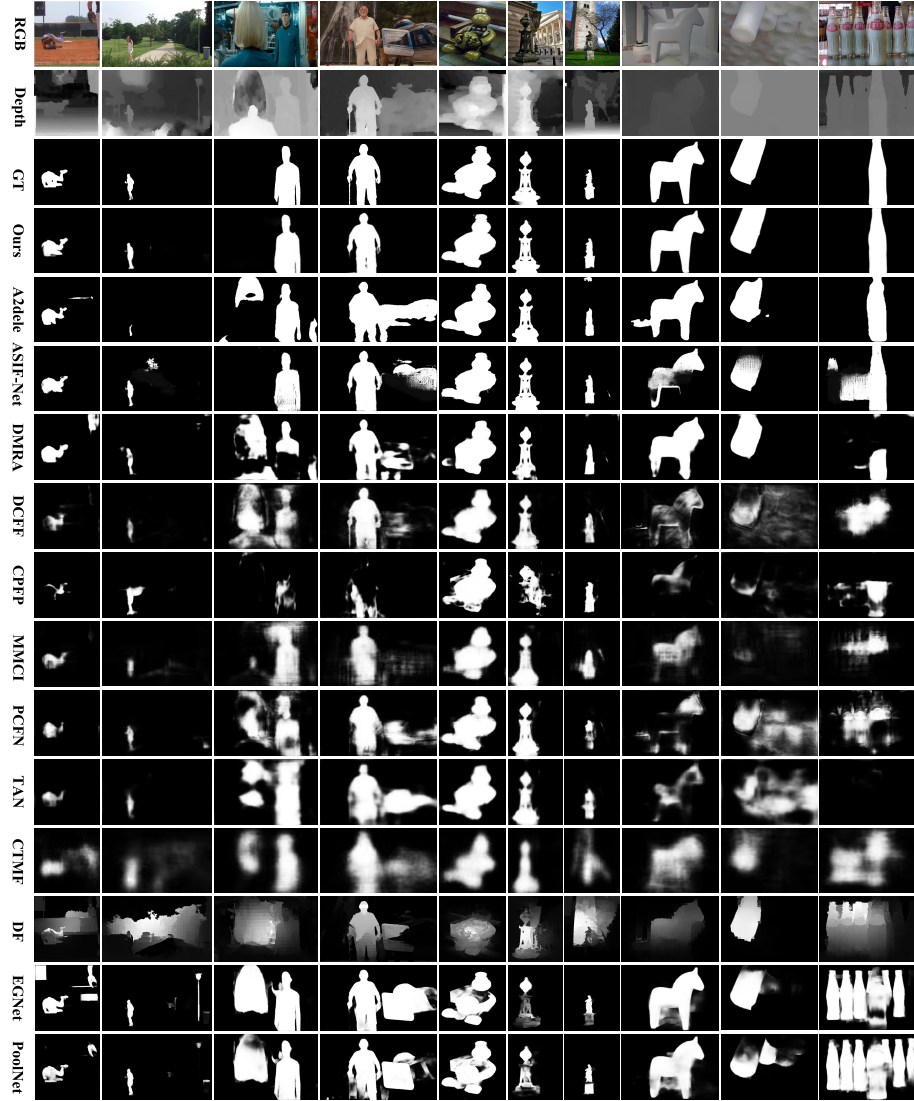


Fig. 1: Visual examples of different methods. From top to bottom are RGB images, the corresponding depth images, ground truth images, our results, the results of A2dele [13], ASIF-Net [9], DMRA [12], DCFE [4], CPF [15], MMCI [5], PCFN [2], TAN [3], CTMF [8], DF [14], EGN [16]), and PoolNet [10].

Table 1: Quantitative comparisons of side outputs in different levels of our network. “best competitor” represents the second best score under each metric in the main manuscript

Levels	STEREO Dataset [11]			DUT-Test Dataset [12]		
	F_β [1] \uparrow	MAE [6] \downarrow	S_m [7] \uparrow	F_β [1] \uparrow	MAE [6] \downarrow	S_m [7] \uparrow
level 1	0.9084	0.0422	0.8895	0.9328	0.0366	0.8853
level 2	0.9076	0.0442	0.8913	0.9319	0.0388	0.8866
level 3	0.9058	0.0504	0.8924	0.9296	0.0450	0.8894
level 4	0.8984	0.0642	0.8862	0.9212	0.0586	0.8843
level 5	0.8839	0.0909	0.8659	0.9057	0.0833	0.8667
best competitor	0.8997	0.0431	0.8778	0.9145	0.0426	0.8637

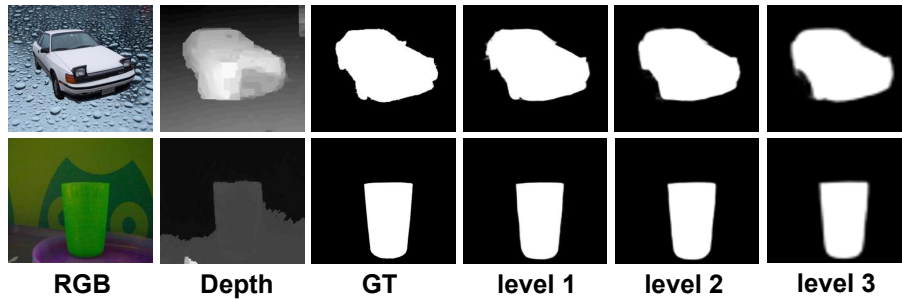


Fig. 2: Visual examples of the side outputs of our network. The sizes of outputs in level 2 and level 3 are up-sampled to the same size as the input RGB image by using linear interpolation.

As shown in Fig. 2 and Table 1, the outputs in level 2 and level 3 also achieve competitive SOD performance when they are compared with the output in level 1, but have faster inference speed. The inference speed of our network in level 1, level 2, and level 3 is 27 FPS, 31 FPS, and 38 FPS, respectively, for a pair of input RGB-D images with a size of 224×224 . As presented in Table 1, compared with the “best competitor” among all the comparisons in the main manuscript, the scores of F-measure and S-measure of the output in level 3 are still higher on the STEREO dataset. Moreover, the scores of F-measure and S-measure of the output in level 4 are still superior on the DUT-Test dataset. In this paper, we treat the output in level 1 as the final result based on its more accurate and robust SOD performance, but have diverse choices by considering the balance of accuracy and inference speed.

3 Model Sizes

In this section, we compare the model sizes of different methods in Table 2. In this comparison, we discard the method of DF [14] because this method contains non-deep learning-based algorithm.

Table 2: The comparisons of model sizes of different methods (in MB)

Method	Ours	PoolNet [10]	EGNet [16]	CTMF [8]	PCFN [2]	MMCI [5]
Model Size	270.4	210.0	432.4	825.8	533.6	929.7
Method	TAN [3]	CPFP [15]	DCFf [4]	DMRA [12]	ASIF-Net [9]	A2dele [13]
Model Size	951.9	278.4	941.5	238.8	323.9	60.1

As presented in Table 2, our method has comparable model size with the state-of-the-art methods such as PoolNet [10], CPFP [15], and DMRA [12], and is more efficient than most compared methods such as EGNet [16], CTMF [8], PCFN [2], MMCI [5], TAN [3], DCFf [4], and ASIF-Net [9].

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